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VASAVI COLLEGE OF ENGINEERING (Autonomous), HYDERABAD
B.E. (CBCS) III-Semester Main Examinations, December-2017

Linear Algebra and its Applications

Time: 3 hours

Max. Marks: 70

Note: Answer ALL questions in Part-A and any FIVE from Part-B

Part-A (10 × 2 = 20 Marks)

1. Give any two examples of vector space.
2. Show that the set of matrices

$$S = \left\{ \begin{bmatrix} -1 & 0 \\ 2 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \right\}$$
 Does not span $M_{2 \times 2}$. Describe span (S).
3. Find $[V]_B$, given $B = \left\{ \begin{bmatrix} 3 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ 2 \end{bmatrix} \right\}$; $V = \left\{ \begin{bmatrix} 8 \\ 0 \end{bmatrix} \right\}$
4. Let V and W be vector spaces, and let $T: V \rightarrow W$ be a linear transformation. Then show that $T(0) = 0$.
5. Define a linear operator $T: R^2 \rightarrow R^2$ by $T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 2x - 3y \\ 5x + 2y \end{bmatrix}$. Show that T is one-to-one
6. Define linear transformation $T: P_4 \rightarrow P_3$ by $T(p(x)) = p'(x)$. Find the null space and range of T .
7. Find the angle between the two vectors $u = \begin{bmatrix} 2 \\ -2 \\ 3 \end{bmatrix}$ and $v = \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix}$
8. Find $\text{proj}_v u$. Where $u = \begin{bmatrix} 3 \\ -2 \end{bmatrix}$ and $v = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$
9. Find the scalar c , so that $\begin{bmatrix} -1 \\ c \\ 2 \end{bmatrix}$ is orthogonal to $\begin{bmatrix} 0 \\ 2 \\ -1 \end{bmatrix}$
10. Define Inner Product Vector Space.

Part-B (5 × 10 = 50 Marks)

(All sub-questions carry equal marks)

11. a) Write all 10 vector space axioms and show that $M_{2 \times 2}$ with the standard component wise operations is a vector space.

- b) Let W be the subspace of all symmetric matrices in the vector space $M_{2 \times 2}$.

$$\text{Let } B = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

show that B is a basis for W and find the coordinates of $v = \begin{bmatrix} 2 & 3 \\ 3 & 5 \end{bmatrix}$ relative to B .

12. a) Let $V = \mathbb{R}^2$ with bases $B = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix} \right\}$ and $B' = \left\{ \begin{bmatrix} 2 \\ -1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right\}$

Find the transition matrix from B to B' . Let $[v]_B = \begin{bmatrix} 3 \\ -2 \end{bmatrix}$ and find $[v]_{B'}$.

b) Let $v_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$ $v_2 = \begin{bmatrix} 0 \\ 2 \\ 21 \end{bmatrix}$ $v_3 = \begin{bmatrix} -3 \\ 4 \\ 7 \end{bmatrix}$ and let $W = \text{Span} \{ v_1, v_2, v_3 \}$.

i) Show that v_3 is a linear combination of v_1 and v_2 .

ii) Show that $\text{span} \{ v_1, v_2 \} = W$.

iii) Show that v_1 and v_2 are linearly independent.

13. a) Define a Mapping $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} x+y \\ x-y \end{bmatrix}$.

i) Find the image of the coordinate vectors e_1 and e_2 under the mapping T .

ii) Give a description of all vectors in \mathbb{R}^2 that are mapped to the zero vector.

b) Define a linear transformation $T: P_2 \rightarrow P_3$ by $T(f(x)) = x^2 f''(x) - 2f'(x) + xf(x)$. Find the matrix representation of T relative to the standard bases for P_2 and P_3 .

14. a) Let V and W be finite dimensional vector spaces and $B = \{v_1, v_2, \dots, v_n\}$ a basis for V . If $T: V \rightarrow W$ be a linear transformation. Then $R(T) = \text{span}\{T(v_1), T(v_2), \dots, T(v_n)\}$,

b) Define $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ by $T\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} x \\ -y \\ z \end{bmatrix}$.

i) Find the matrix of T relative to the standard basis for \mathbb{R}^3 .

ii) Use the result of part (a) to find $T\left(\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}\right)$

15. a) State and prove triangle inequality on vector spaces.

b) Let $u = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$ and $v = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$.

i) Find $\text{proj}_v u$.

ii) Find $u - \text{proj}_v u$ and verify that $\text{proj}_v u$ is orthogonal to $u - \text{proj}_v u$.

16. a) If $S = \{v_1, v_2, \dots, v_n\}$ is an orthogonal set of nonzero vectors in an inner product space V , then prove that S is linearly independent.

b) Let $V = P_2$ with inner product defined by $\langle p, q \rangle = \int_{-1}^1 p(x)q(x)dx$.

i) Show that the vectors in $S = \{1, x, \frac{1}{2}(3x^2 - 1)\}$ are mutually orthogonal.

ii) Find the length of each vector in S .

17. Answer any *two* of the following:

a) Let $S = \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ -2 \end{bmatrix} \right\}$ find the basis for span of S.

b) Let $T: R^3 \rightarrow R^3$ be a linear operator and $B = \{v_1, v_2, v_3\}$ a basis for R^3 . Suppose that

$$T(v_1) = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \quad T(v_2) = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \quad T(v_3) = \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}$$

i) Is $\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$ in $R(T)$?

ii) Find a basis for $R(T)$.

c) Let $V = R^3$ and $u = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$ and $v = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$ be vectors in V . let k be a fixed positive real number, and define the function $\langle \cdot, \cdot \rangle: R^2 \times R^2 \rightarrow R$ by $\langle u, v \rangle = u_1 v_1 + k u_2 v_2$. Show that V is an inner product space.

